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2.2 4
2.3 5
2.4 6
3 7
3.1 7
3.2 10
4 11
4.1 11
4.2 11
4.3 12
4.4 12
5 13
5.1 13
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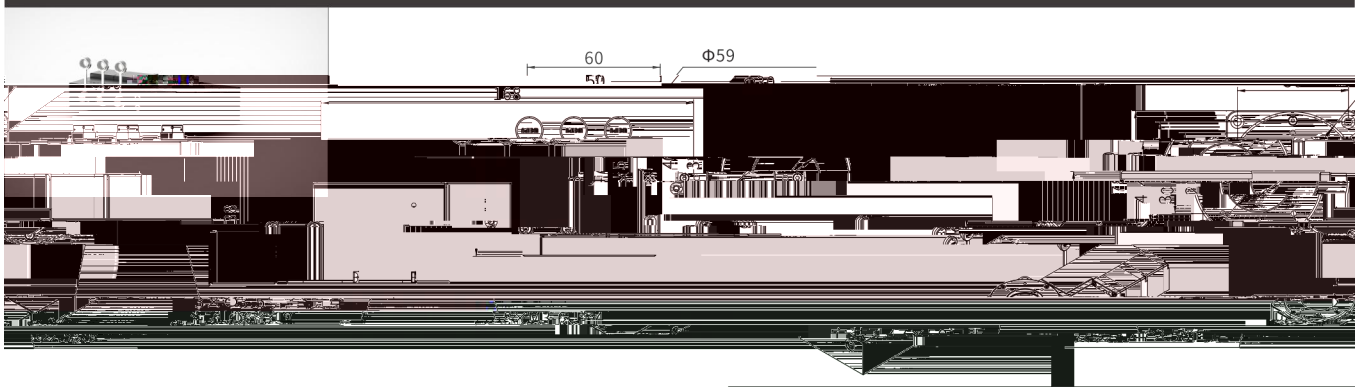
Window Linux C/C++ C# Matlab LabVIEW

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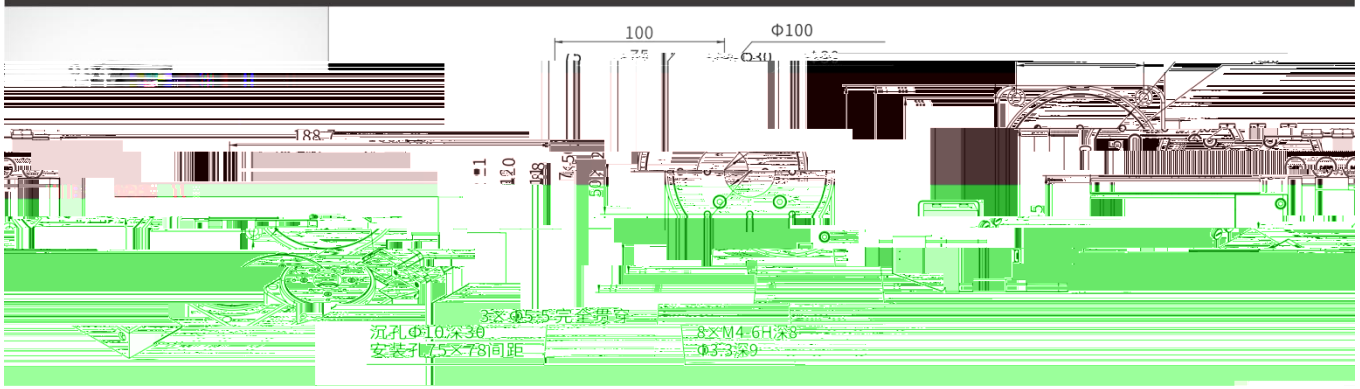
: IMCR100 ~ +~ 100mm

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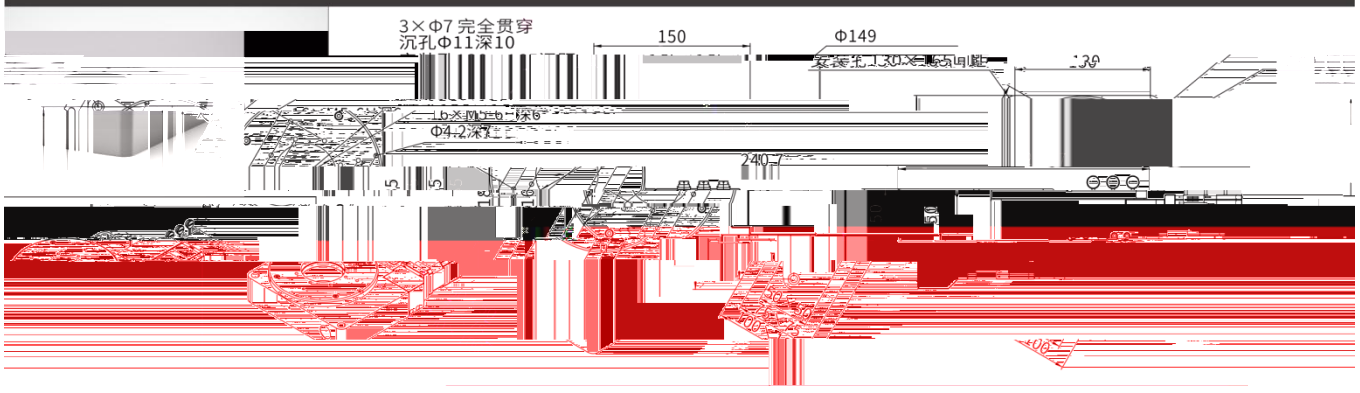
IMCR60

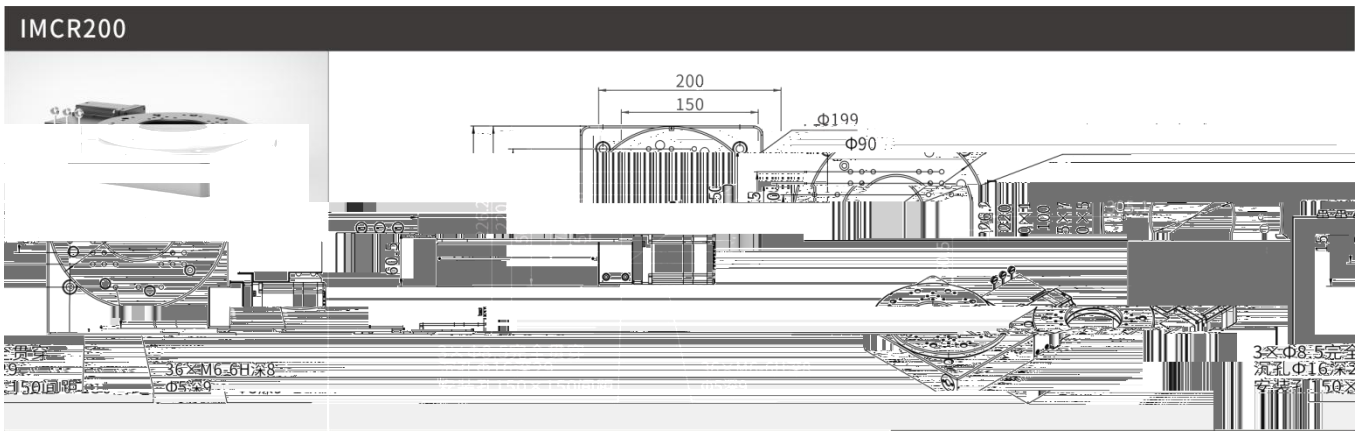


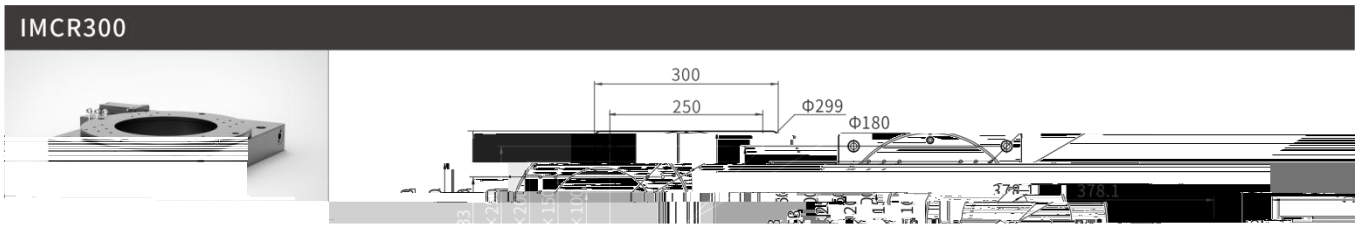
IMCR100



IMCR150







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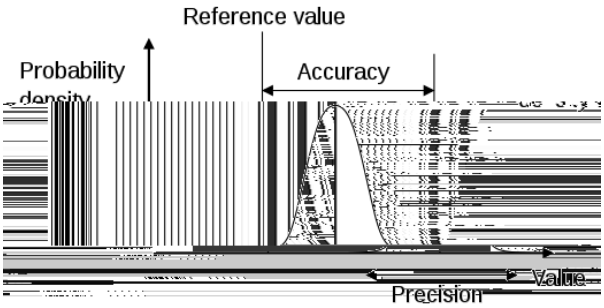
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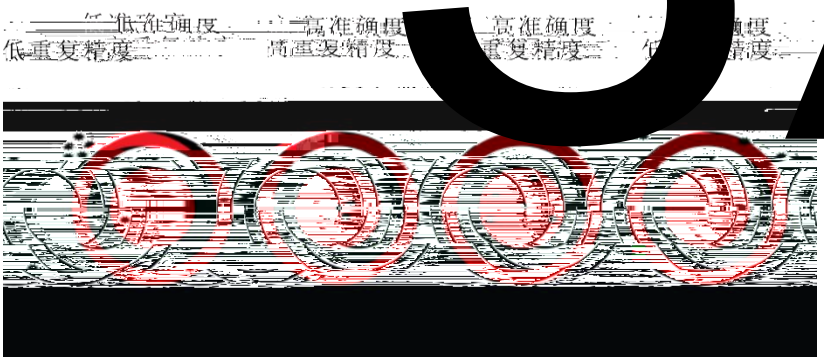
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Model	IMCR60	IMCR100	IMCR150	IMCR200	IMCR300
Travel(°)	360	360	360	360	360
Load Capacity(Kg)[1]	20	40	50	60	120
Resolution(°)	0.005	0.005	0.005	0.005	0.005
Min.Incremental Motion(°)[2]	0.01	0.01	0.01	0.01	0.01
ّ ن ع Bi-Directional Repeatability(°)	±0.01 or 0.02	±0.01 or 0.02	±0.01 or 0.02	±0.01 or 0.02	±0.01 or 0.02
Accuracy[3](°)	±0.05 or 0.1	±0.05 or 0.1	±0.05 or 0.1	±0.05 or 0.1	±0.05 or 0.1
Max.Speed(°/s)[4]	20	20	20	20	20
Weight(kg)	0.6	1.57	4.5	8.37	17.75

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[2] n سر

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[3] سر أ ّ

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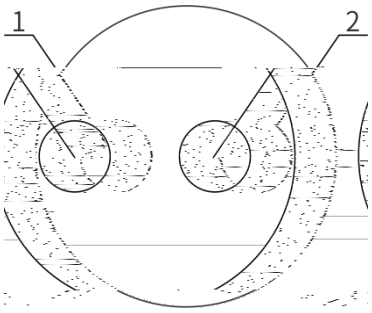
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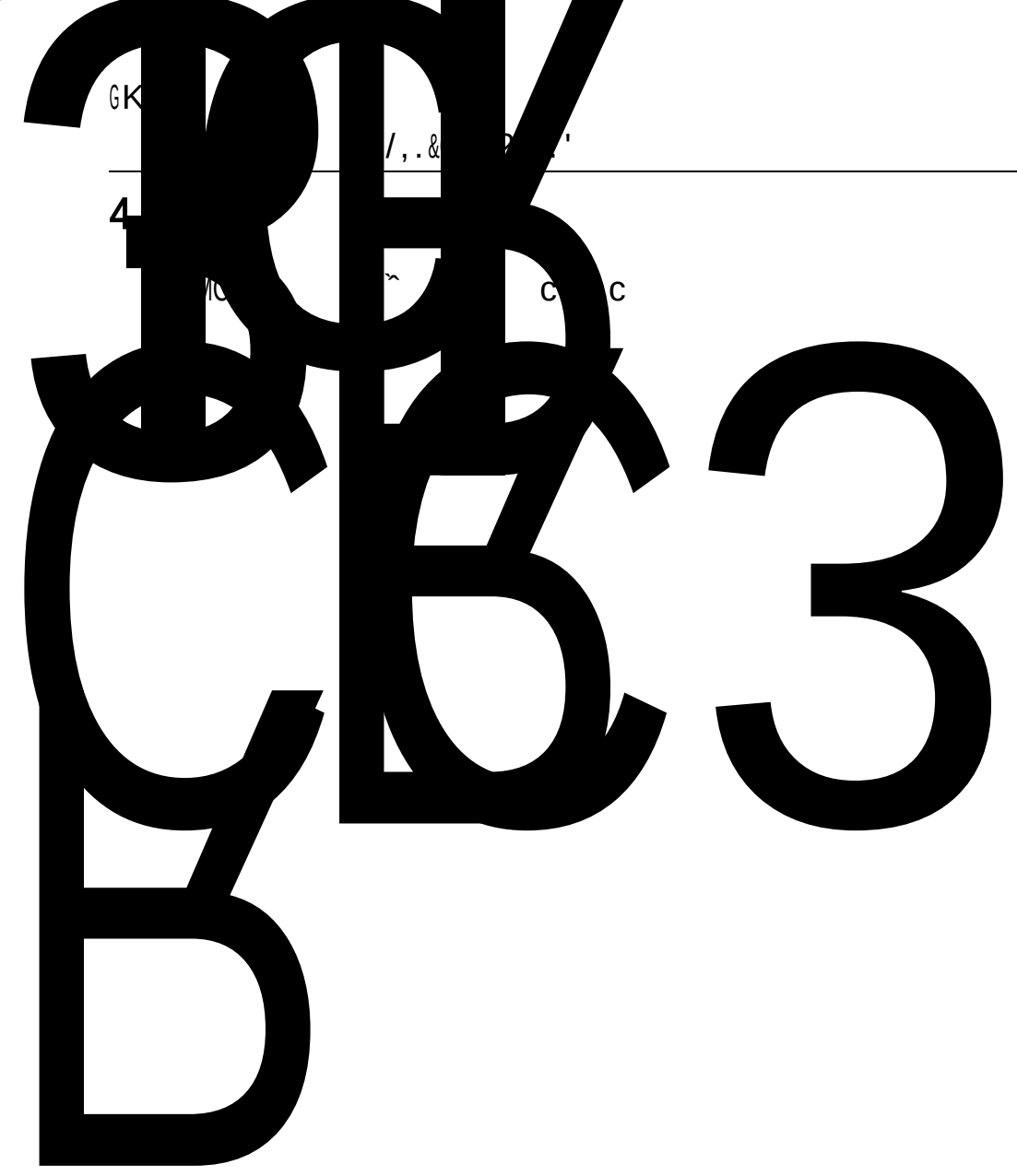
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۶ Electric wiring diagram			
 2			
	2		
	1	24V+	DC24V
	2	24V-	DC24V
	3		
	1	485A	
	2	485B	
	3	PE	غي
 3	3		
	1	485A	
	2	485B	
	3	PE	غي

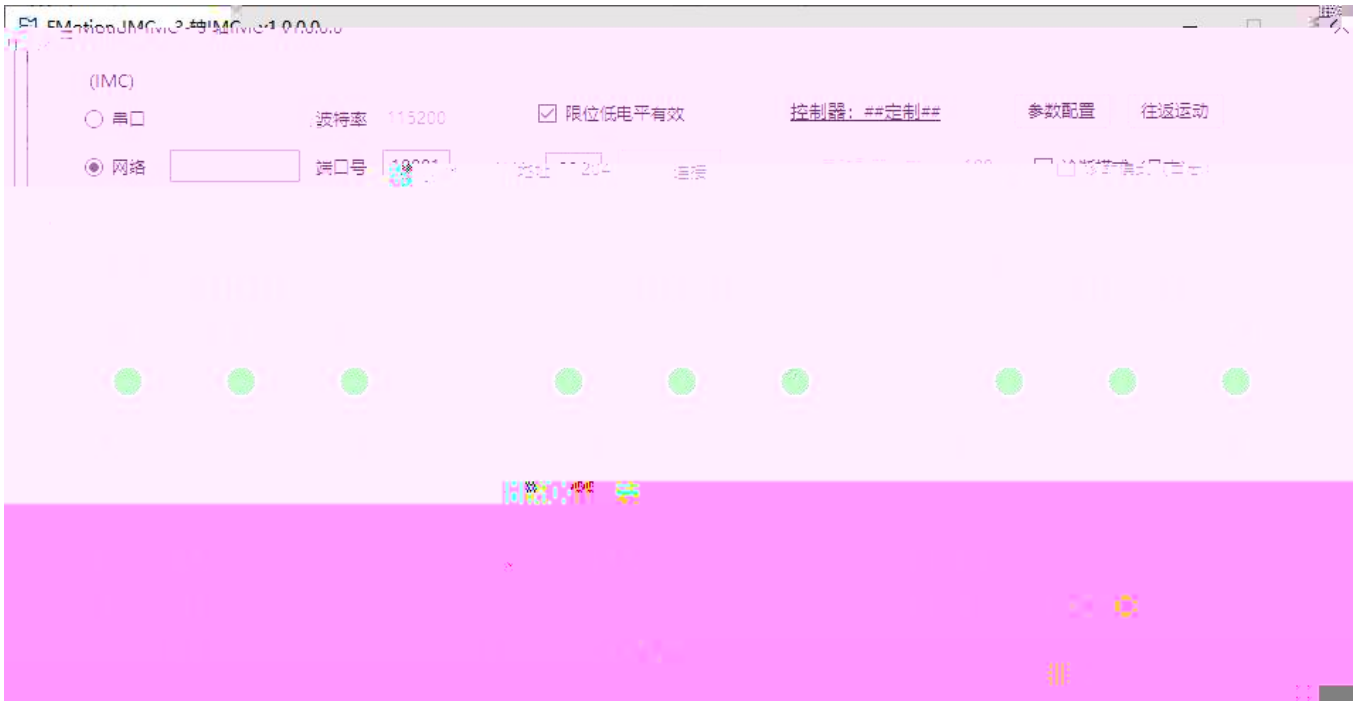


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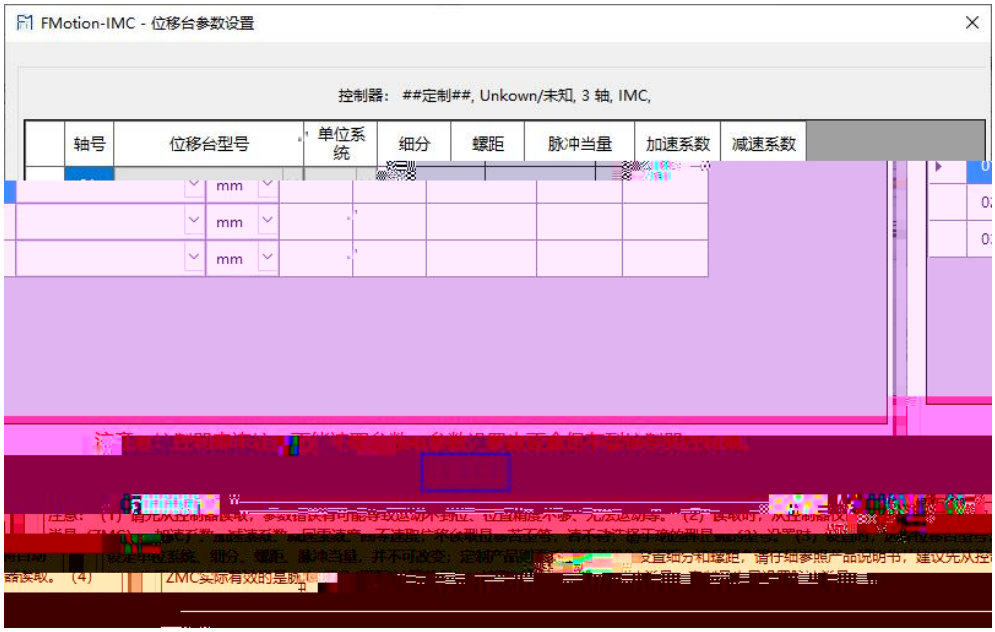
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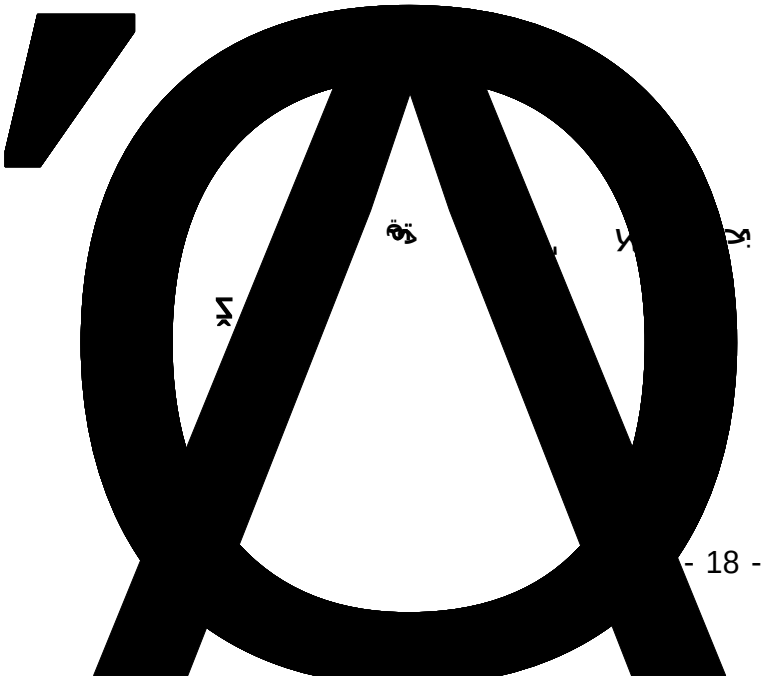
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شح:http://www.feinixs.com